

# OMNI 2400 GDS™

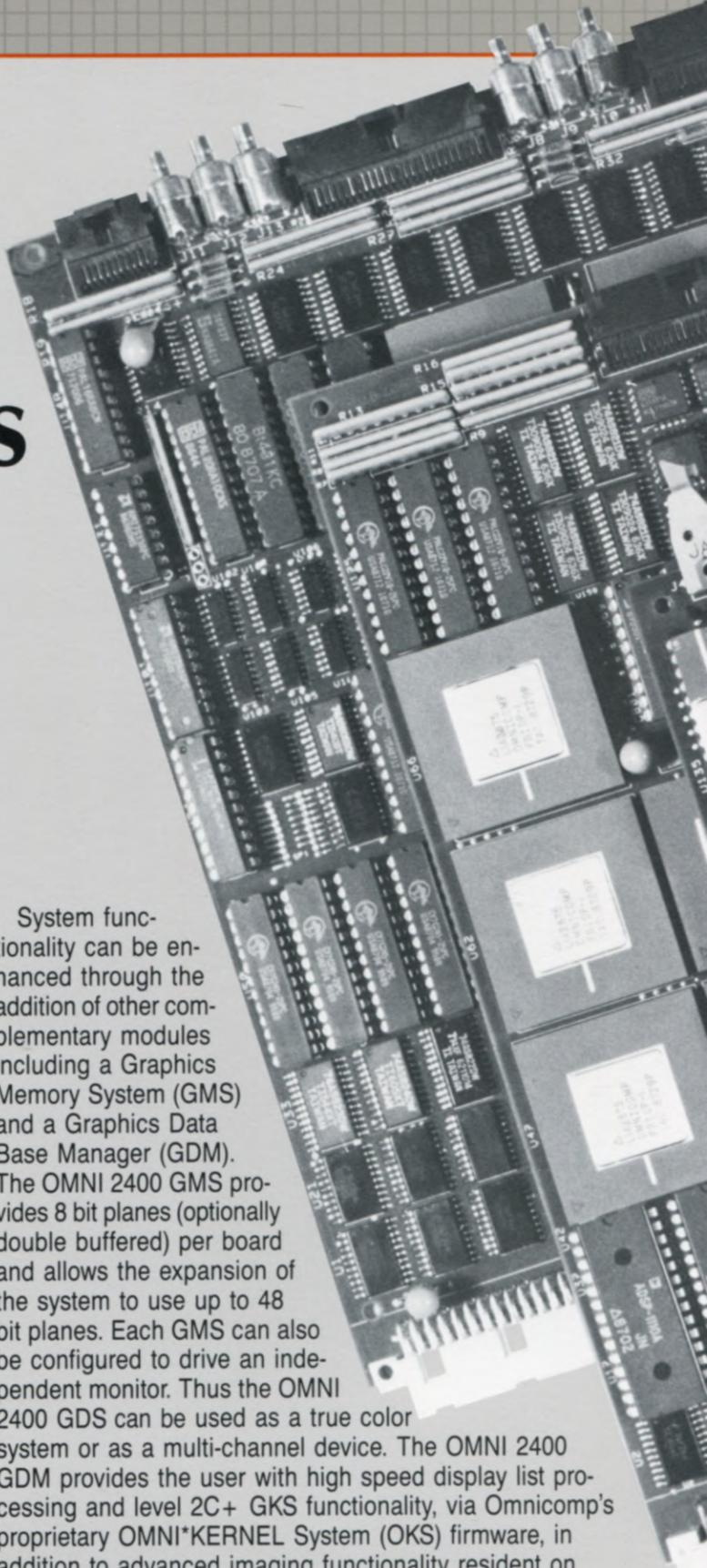
## The High Performance OEM Graphics Subsystem

The OMNI 2400 GDS incorporates both high performance raster graphics and image processing in a single system. Additionally, this system supports multiple, independent graphics channels or true color capabilities.

The OMNI 2400 GDS is available as a traditional packaged system with DEC compatible parallel interfaces or as a board level system with an Intel MULTIBUS II system bus interface. By combining sophisticated graphics system design techniques with a high performance public bus structure, the OMNI 2400 GDS provides an opportunity for system developers to integrate high performance vector and image graphics with powerful computing platforms on the same system bus.

The OMNI 2400 GDS is a modular, multiple board system which conforms to the MULTIBUS II 6U x 220mm form factor. Two system interfaces are provided: P1 - the standard iPSB interface using the message passing protocol, and P2 - the interface to the GBX-II bus, passing control and data signals unique to the OMNI 2400 GDS (see figure 1).

A minimum OMNI 2400 GDS system consists of two modules, the Graphics Control Processor (GCP) and the Graphics Output System (GOS). This configuration provides seven mips bit slice geometry processor (GCP), a seven mflops floating point coprocessor, a proprietary vector coprocessor, a graphic input device controller, four planes of 1280 by 1024 display memory, a hardware cursor, and a 60 Hz non-interlaced (112 MHz) video output channel.



System functionality can be enhanced through the addition of other complementary modules including a Graphics Memory System (GMS) and a Graphics Data Base Manager (GDM). The OMNI 2400 GMS provides 8 bit planes (optionally double buffered) per board and allows the expansion of the system to use up to 48 bit planes. Each GMS can also be configured to drive an independent monitor. Thus the OMNI 2400 GDS can be used as a true color system or as a multi-channel device. The OMNI 2400 GDM provides the user with high speed display list processing and level 2C+ GKS functionality, via Omnicomp's proprietary OMNI\*KERNEL System (OKS) firmware, in addition to advanced imaging functionality resident on the Graphics Control Processor module.

# OMNI 2400 GDS™

## Graphics Control Processor

The Graphics Control Processor (GCP) is a graphic drawing engine, an image manager and a geometry processor. All GCP functions are controlled by a highly parallel seven mips AMD 29116 based bit slice processor which uses a 72 bit wide microword instruction. A seven mflops floating point coprocessor, the AMD 29325 floating point ALU, communicates with the bit slice processor through a dual ported 8 KByte scratch RAM.

The bit slice processor provides significant flexibility in the application functionality of the OMNI 2400 GDS. This processing power is easily applied to both geometry processing and digital filtering. The design of the microcode takes full advantage of this resource by providing commands for two and three dimensional vector and polygon oriented functions as well as image analysis and processing operations. In addition to vector and polygon draw, transform, and zoom operations; a convolution function provides digital image filters including Laplace, high, and low pass. Spatial and logical operations are also provided.

The GCP communicates with the host CPU through DEC compatible parallel interfaces or through the iPSB interface. Efficient data transmission is maintained with both data channels by using buffered fifo's. Also included within the GCP module is a peripheral coprocessor which supports four RS-232 serial data ports. This Intel 80188 based coprocessor provides a direct link between a graphics locator device, such as a mouse or digitizer, and the graphics cursor generator. This offloads the cursor positioning responsibilities from the drawing engine.

For applications which require a variety of rapidly generated bit mapped text fonts, the GCP contains 40 KBytes of high speed memory which may be downloaded with custom text fonts. A typical 15 pixel wide by 20 pixel high bit mapped text character is drawn in less than 10 microseconds. Bit mapped text may be clipped, pixel by pixel, to an arbitrary screen viewport with no performance penalty.

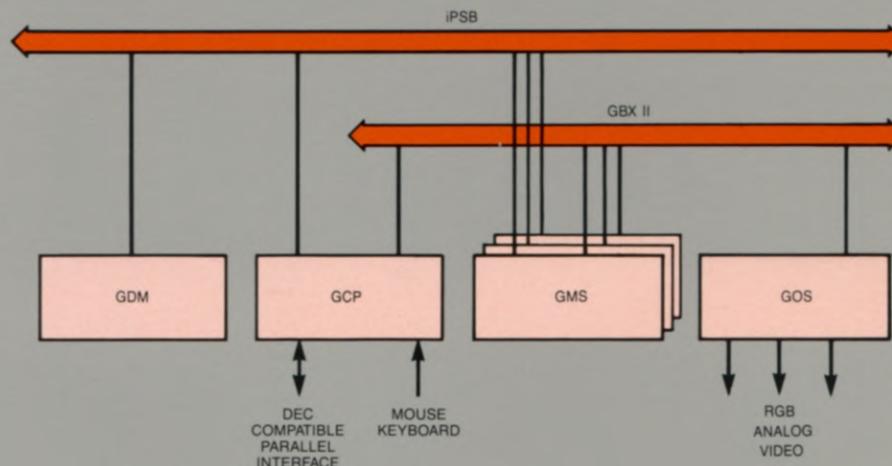
The primary function of the GCP is to execute drawing and image manipulation commands which are passed to it either by the GDM or by the host CPU. The GCP is capable of proces-

sing drawing primitives specified in both screen and world coordinate systems. Those drawing primitives which are specified in the world coordinate system are first converted to screen coordinates by the floating point coprocessor. The conversion process consists of a general geometric transformation, followed by a clipping operation and finally a window to viewport mapping. The bit slice processor converts screen coordinate drawing primitives and raster image data into a series of data words and control signals used by the vector coprocessor.

The 14 MHz vector coprocessor utilizes proprietary logic developed by Omnicomp Graphics Corporation. This coprocessor is capable of generating vectors of any orientation at the rate of one pixel per 70 ns and bit mapped text at ten microseconds per character.

In order to de-couple the vector coprocessor from the system frame buffer, a 20 pixel cache is employed. The pixel cache is organized as a 5 pixel by 4 pixel array. The entire contents of the pixel cache can be written to an arbitrary location within the frame buffer in a single frame buffer memory cycle of 430 ns.

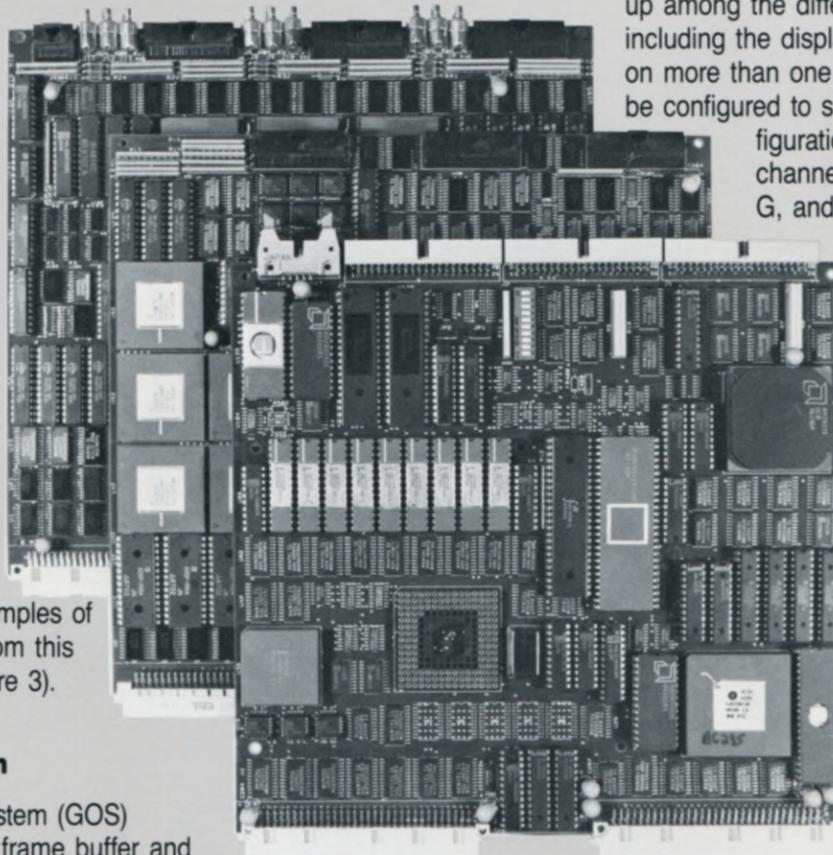
Figure 1: The OMNI 2400 GDS system consists of a minimum of two modules: the graphics control processor (GCP) and the graphics output system (GOS) module. Added functionality can be obtained by using a graphics memory system (GMS) module and a graphics database manager (GDM).



Because of the 5 by 4 pixel cache and the proprietary coprocessors, the OMNI 2400 GDS can sustain a throughput of over 200,000 forty pixel vectors per second. This unique architecture minimizes the number of frame buffer accesses required for typical drawing operations and facilitates highly efficient execution of all graphic primitives. Fat lines, patterned fills, patterned lines, irregular fills, polymarkers, bit mapped text and paint brush style strokes are examples of operations which benefit from this drawing efficiency (see figure 3).

### Graphics Output System

The Graphics Output System (GOS) module provides the video frame buffer and video output functions required by the OMNI 2400 GDS. Each system contains a single GOS module which allows for the attachment of one to three independent monitors. The three independent RGB video channels will support a single GMS per RGB channel. The overlays may be split



up among the different heads in any fashion, including the display of a single overlay plane on more than one head. The GOS may also be configured to support a true color configuration in which the three video channels are used as separate R, G, and B channels.

The GOS module contains four planes of frame buffer memory. Video data generated by these planes may overlay the video data received from the optional GMS modules. The GOS multiplexes the data bits it receives from the GMS into a 112 MHz video signal. The video data stream is then routed to the color palettes, which provide the color look up and digital to analog signal conversion functions. When

configured with a GMS, the OMNI 2400 GDS provides a palette of 16.7 million colors (see figure 5). A separate overlay color look up table is used to control how the overlay video data affects the primary video signal. Systems configured without a GMS module use the GOS

Figure 2: All GCP functions are controlled by an AMD 29116-based bit-slice processor. The GCP communicates with the host through either a DEC-compatible interface or the MULTIBUS II's iPSB.

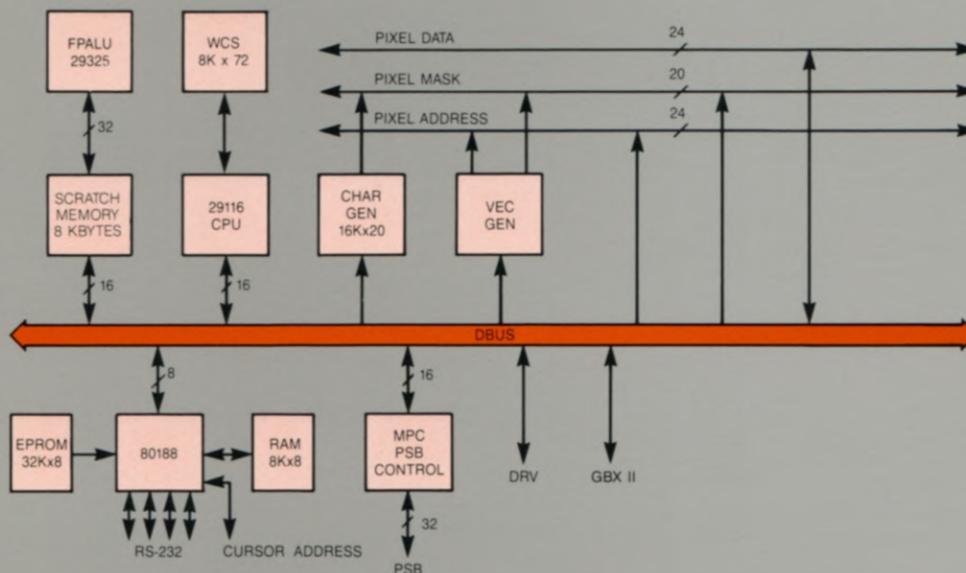


Figure 3: If each pixel in the vector represented in (A) were drawn individually, 15 memory cycles would be required. By allowing simultaneous access of the two-dimensional regions of the frame buffer, only three memory cycles are required. If the text character represented in (B) were drawn using a pixel block transfer, a frame buffer that allows only scan-line access would require 12 memory cycles to complete the transfer, the GDS requires only six memory cycles.

frame buffer to provide a 16 color display.

In order to simplify the use of the graphic cursor, the GOS provides a hardware generated matrix and cross-hair cursor. By generating the graphic cursor on the fly rather than by drawing it into a frame buffer plane, any interference between frame buffer data and the cursor is removed. The cursor video signal is routed through the overlay look up table to allow the cursor display characteristics to be adjusted.

### Graphics Memory System

The graphic memory system (GMS) module provides up to 1280 x 1024 x 16 frame buffer memory in multiple configurations. By employing dual ported video RAM in the GMS design rather than conventional DRAM, a more efficient frame buffer memory organization is made possible. By combining three GMS modules together, a 48 plane, true color, double buffered system can be configured. In addition, each GMS may have its eight plane buffer as additional overlay planes; as a 16 pixel memory

in conjunction with the first buffer, where any eight contiguous planes can be displayed; or as a 1280 x 2048 x 8 image memory.

The frame buffer implementation, used by the OMNI 2400 GDS maximizes the frame buffer input bandwidth and allows multiple scanlines to be accessed simultaneously. This results from the fact that most drawing operations execute with fewer frame buffer accesses when small two dimensional regions of the frame buffer may be accessed at once rather than by a single scan line. The OMNI 2400 GDS frame buffer memory is organized as 256 rows by 256 columns of 5 pixel by 4 pixel words. This memory organization is possible due to the dual ported video RAM's high serial output port bandwidth, which allows a narrow frame buffer word to provide the required frame buffer output bandwidth.

Physically, each 5 by 4 pixel word consists of 20 pixels which share a common memory address. In order to further reduce the number of frame buffer accesses, the frame buffer design allows the contents of the pixel cache to be written to any location within the frame buffer in a single

memory cycle, without regard to the physical frame buffer word boundaries. Each pixel within the frame buffer cell is individually addressable. A two-dimensional barrel shifter is used to compensate for misalignment between the contents of the pixel cache and the fixed cell boundaries of the frame buffer.

Each GMS contains five proprietary gate arrays for direct pixel processing and rapid pixel transfer of data from the iPSB. Coupled with multipliers, these provide the Single Instruction Multiple Data (SIMD) architecture which provides up to 80 mips of performance per GMS module. Up to five megabytes of data per second can be transferred to and from the iPSB per second. This unique design allows the OMNI 2400 GDS to move data from local bus storage or local disk storage at animation speeds.

The GOS/GMS architecture also permits hardware zoom and pan of the display buffers.

### Serial Versus Parallel

Another form of block pixel transfer is used by the GMS to transfer data from one set of frame buffer planes to

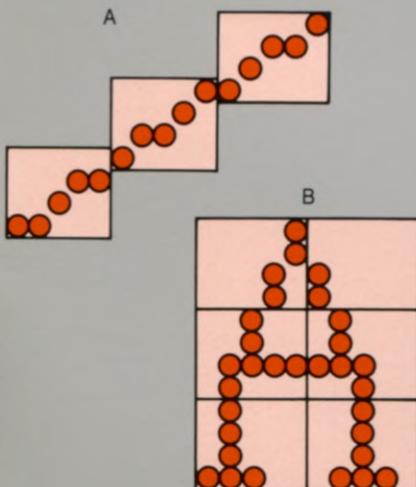
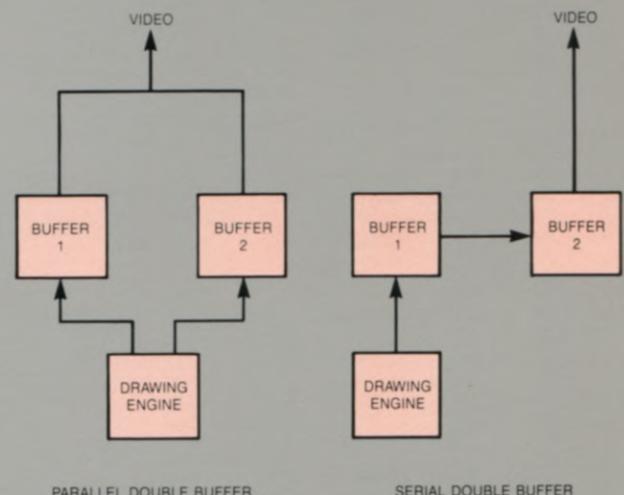


Figure 4: Serial double buffering is often more efficient than the traditional parallel double buffering method. The parallel double buffer uses two identical buffers—as one buffer is accessed by the drawing processor, the other buffer is displayed. A serial double buffer dedicates one buffer as a drawing buffer and another as a display buffer.



another, thus providing a serial double buffering capability. Double buffering is used to delay the visual effects of drawing operations until the drawing is complete. Serial double buffering, as it is employed by the OMNI 2400 GDS, is often significantly more efficient than the traditional parallel double buffering method. The parallel double buffer employs two identical buffers. As one buffer is accessed by the drawing processor, the other buffer is displayed. When the drawing is complete the original drawing buffer becomes the display buffer, and the original display buffer becomes the current drawing buffer. The parallel double buffer is convenient if the entire buffer content is regenerated before each buffer swap. If, on the other hand, only a portion of the buffer content is modified, such as in a multiple window display, the parallel double buffer is much less convenient. Because the most recent modifications to the display buffer are not reflected in the current drawing buffer, they must be duplicated in the drawing buffer before the current drawing activity may proceed. This redundant activity significantly affects both system

performance and operating overhead (see figure 4).

A serial double buffer on the other hand dedicates one buffer as a drawing buffer and another as a display buffer. As a drawing is completed the contents of the drawing buffer are transferred into the display buffer. The OMNI 2400 GDS performs this block transfer in a single video frame time of 16.667 milliseconds. Each pixel is moved from the drawing buffer to the display buffer just after the display pixel is sent to the screen. This results in an apparently instant change in the display. By employing a dedicated drawing buffer, the inefficiencies of the traditional double buffering method are removed. Because the data transfer from the drawing buffer to the display buffer does not impede the drawing process, the double buffer may be made transparent by constantly enabling the transfer. The OMNI 2400 GDS supports parallel double buffering as well.

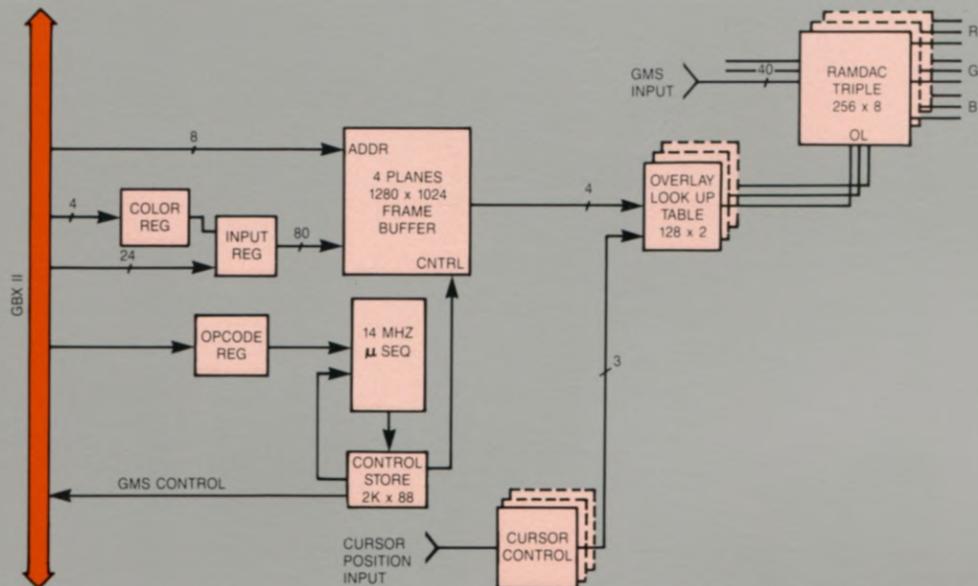
### Graphics Database Manager

The GDM module is an Intel 80386/80387 based CPU and memory board and is configured as a back-

end processor. This allows the bit slice drawing processor to scan the incoming command stream and execute any commands targeted for it. The GDM connects to other system modules via the iPSB bus interface. A 64 Kbyte memory cache is used to allow the 80386/80387 to run at 16 MHz with no wait states. A large display list store, consisting of up to 16 Mbytes of memory, is connected directly to the 32 bit wide memory cache.

The display list operations executed by the GDM correspond directly to standard host based GKS subroutine calls. By using the same OMNI\*KERNEL System firmware as other Omnicomp products, the philosophy of providing upward compatibility throughout its family of graphics systems has been retained. Thus, the systems integrator has a price/performance range of software compatible graphics devices with which to address his marketplace requirements. This firmware is written entirely in 80386 assembly language and executes in a stand alone fashion, with no intervening operating system. The responsibilities of the GDM are to manage the data base and graphic attribute control functions.

Figure 5: The graphics output system (GOS) module contains four planes of frame buffer memory, an overlay look-up table and up to three channels of video interface. Systems configured without a graphics memory system (GMS) module use the GOS frame buffer to provide either a double buffered sixteen-color display.



## Designed for the OEM

The modular nature of the OMNI 2400 GDS allows system expansion and enhancement to occur in an incremental manner. The overall design philosophy behind the OMNI 2400 GDS is to provide a family of board level components which may be combined to provide a standard set of high performance graphic display functions.

Graphics display subsystems must be designed to meet the widely varying requirements of OEM's and system inte-

grators. Modular flexibility allows those requirements to be met without the customer purchasing more features than necessary. A modular design also enables the manufacturing company to evolve the subsystem; incorporating new semiconductor innovations, keeping it price/performance competitive. The OMNI 2400 GDS was conceived to meet the needs of a broad spectrum of applications. As such, it must remain both a physical product and a design concept. As it evolves over the coming years, most of the currently used components

will be designed out in favor of parts providing denser integration, more performance and better economics. What will remain is the concept of what its functionality must be, the algorithms used to provide that functionality and the buses and pathways linking all of its parts internally and externally. The modularity, the security of standards, and the growth path gained from conformance to MULTIBUS II (IEEE P1296), ISO GKS and other accepted design approaches will allow these changes to be well thought out and manageable.

## Features

- Modular Configurations
- MULTIBUS II iPSB and DR11-W Interfaces
- High Speed 2D and 3D Geometry Processing
- GKS Display List Processor/Manager
- Highly Parallel, Pipelined Architecture
- Non-destructive Overlay Planes
- Hardware Cursor
- Region of Interest Processing
- Serial Double Buffering
- Image Processing Commands
- Monochrome to True Color
- Very Fast Pixel Draws:
  - Vectors: Up to 10 Megapixels per Second
  - Fills: Up to 40 Megapixels per Second
  - BLT: 20 Megapixels per Second
- Very High Speed Bit-Mapped Characters

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*Optimizing Computer Graphics... by Design.*

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## Specifications:

### Display Characteristics:

- 1280 x 1024 Display Resolution
- 60 Hz Non-interlaced or 30 Hz Interlaced
- Hardware Screen Clipping
- Hardware Matrix and Crosshair Cursors
- 4 Overlay Planes
- 1, 2 or 3 Displays

### Display Memory Configurations:

- 4 Planes
- 8 Planes
- 8 Planes Double Buffered
- 2 x 8 Planes - Twin Heads
- 3 x 8 Planes - Triple Heads or True Color
- 2 x 8 Planes - Twin Heads, Double Buffered
- 3 x 8 Planes - Triple Heads or True Color, Double Buffered

### Display List Memory: 1, 4 or 16 Mbytes

### Multiple Processors:

- GCP: Geometry Processor - 29116 Bit Slice
- Floating Point Coprocessor - 29325 FPP
- Primitive Coprocessor - Discreet TTL
- Peripheral Coprocessor - 80188
- GMS: Five Pixel Processors - proprietary gate arrays and ADSP-110 multiplier
- GOS: Frame Buffer Control Processor - 14 MHz Bit Slice
- GDM: Display List Processor - 80386
- Floating Point Coprocessor - 80387

### Power Requirements:

- 310 Watts @ 110 VAC - typical

### Host Interfaces:

- MULTIBUS II iPSB
- 16-Bit Parallel DMA
- (DRV11-WA/DR11-W)

### Video:

- RS-343 RGB, Composite Available
- Pixel Clock: 112 MHz Non-interlaced
- 56 MHz Interlaced

Specifications subject to change without notice.

Printed in USA

## OMNI 1000 GDC™/OMNI 1200 GDC™ TECHNICAL OVERVIEW

The OMNI 1000/1200 Graphics Display Controllers (GDC) establish a new standard in price performance, versatility and proven reliability. The OMNI 1000 GDC/OMNI 1200 GDC single board graphics controllers combine innovative engineering with efficient manufacturing management to provide unequalled cost effective solutions for graphics display requirements. The OMNI 1000 GDC/OMNI 1200 GDC are major advances in high performance GKS display graphics for applications relating to the fields of mechanical and electronics design, AEC, cartography and geoseismic evaluation.

### FEATURES

- Innovative design techniques provide high performance, reliability and low price in a single board
- OMNI\*KERNEL System (OKS) firmware provides Draft ANSI and enhanced ISO GKS compatible functionality.
- Display resolution is firmware definable from 512 x 512 pixels to 1280 x 1024 pixels
- Image memory of 1024 x 1024 pixels or 2048 x 2048 pixels
- Instantaneous vector drawing speed of 1.5 million eight bit pixels per second
- 256 colors simultaneously displayed from a palette of 4096 or 16.7 million colors
- Multiprocessor design augmented by VLSI graphics controller
- On-board display list processing
- Firmware support for a wide variety of graphics input devices and peripherals

### INNOVATIVE FLEXIBILITY AND ECONOMICAL PERFORMANCE

By exercising engineering innovation, incorporating public design standards and utilizing cost effective semiconductor technology, Omnicomp can offer the user a superior price performance value. The OMNI 1000 GDC/OMNI 1200 GDC incorporate the reliability of single board packaging, the adaptability of complete bus independence, the performance of a firmware encoded instruction set, ISO GKS Standard compatibility and a distributive multiprocessor architecture.

### Single Board Reliability

Many mechanical connectors, a major cause of electronics system failures, have been eliminated by designing the products as single boards. In the event that service is required, replacing a single circuit board corrects any difficulties.

### Bus Independent

The OMNI 1000 GDC/OMNI 1200 GDC are designed to support parallel communications with most computers at speeds of one million bytes per second. DMA interfaces are available for UNIBUS, Qbus, MULTIBUS, VME as well as the primary buses for other popular computer systems. High speed parallel I/O interfaces are also available for the Intel MULTIBUS iSBX, IBM bus and IBM PS-2 microchannel. Serial RS 232-2 communications at speeds up to 19.2 Kilobaud are supported.

### Distributive Multiprocessor Architecture

The architecture of the OMNI 1000 GDC/OMNI 1200 GDC optimizes graphics throughput by utilizing both general and special purpose microprocessors to accomplish different tasks. A general purpose 16-bit microprocessor manages generalized I/O, processes display list segments and executes OKS firmware instructions. A floating point numeric co-processor accelerates all arithmetic operations. A specialized I/O processor manages bulk pixel transfers and controls DMA operations. A VLSI graphics controller manages all operations involving image memory.

### Flicker-Free Interlaced Display

The OMNI 1000 GDC/OMNI 1200 GDC feature 1024 x 1024 display resolution at 34Hz interlaced refresh rate to provide flicker-free operation with a low cost monitor. Under firmware control the OMNI 1000 GDC/OMNI 1200 GDC can also operate in a non-interlaced mode at 1024 x 768 or lower resolution.

### COMPLETE SUPPORT REDUCES APPLICATION IMPLEMENTATION EFFORT

Even the most advanced computer hardware is of limited utility until properly integrated with complementary hardware and application software. Omnicomp recognizes that the customer's investment in integration and application software is important. A complete support library, detailed documentation, custom service and a broad range of available interfaces minimize any integration and application development expense with the OMNI 1000 GDC/OMNI 1200 GDC.

## OMNI\*KERNEL SYSTEM

An important feature of the OMNI 1000 GDC/OMNI 1200 GDC is the OKS firmware. OKS is a complete 2D graphics package, including functional compatibility with the ISO GKS Standard in firmware. Additionally, OKS includes extensions commonly used in graphics applications, but not accommodated by GKS, such raster operations and planar Boolean operations. By providing firmware to perform all graphics computations external to the host computer, the OMNI 1000 GDC/OMNI 1200 GDC free host resources for applications. In most cases, graphics operations are performed more quickly than if the same task were executed by the host computer. Address space is available for the addition of customer defined firmware instructions. Some of the categories of functionality provided by OKS are:

- o SYSTEM CONTROL
- o RASTER OPERATIONS
- o SEGMENT MANIPULATION
- o DATABASE OPERATIONS
- o DISPLAY CONTROL
- o ECHO OPERATIONS
- o PLANE MANIPULATIONS
- o PRIMITIVES
- o SET/INQUIRE CURRENT ATTRIBUTES
- o SET/INQUIRE SEGMENT ATTRIBUTES
- o COLOR CONTROL
- o WINDOW/VIEWPORT CONTROL
- o REQUESTS
- o SAMPLE DEVICE

## OKLIB

All OKS operations are fully supported by OKLIB, a compact host graphics software library available in FORTRAN or C. Site specific licenses are available for source, or object forms, of OKLIB.

## CONFIGURATION FLEXIBILITY

The OMNI 1000 GDC/OMNI 1200 GDC is available as a stand-alone circuit board, table top system, or within a 19" rack mount chassis. Each OMNI 1000 GDC/OMNI 1200 GDC can be ordered to meet customer requirements regarding display resolution, image memory size and custom firmware.

## TECHNICAL SPECIFICATIONS

### System Processors

- 8086 General Purpose Processor (8MHz)
- 8087 Floating Point Processor (8MHz)
- 8089 I/O Processor

System Memory

256 Kilobytes of Display List  
64 Kilobytes of OKS or Custom Firmware

Display List Capacity

Segmented Architecture: 1024 Segments  
4096 Primitives  
32,768 Endpoints

Graphics Controller

7220 Graphics Display Controller, Cycle Time 167 ns

Image Memory

1024 x 1024, 8 Planes; or 2048 x 2048, 8 Planes

Host Interfaces

16 Bit Parallel Programmed I/O (DRV11 or DR11-C)  
16 Bit Parallel DMA (DRV11-B or DR11-W)  
Serial RS-232C, Maximum 19.2 Kbaud

Display Interface

RS-343 RGB Video, Composite Available

Local Device Interfaces

Mouse, Data Tablet, Keyboard, Joystick, Thumbwheels, Trackball and Touch Screen

Cursor

Non-destructive

Operating Environment

Temperature: 50°F to 95°F (10°C to 35°C)  
Humidity: 10% to 90% Non-condensing  
Altitude: 8,000 Feet (2,400 Meters)

Power Requirements

90-132 VAC, 60 Hz  $\pm$  2%  
180-264 VAC, 50 Hz  $\pm$  2%  
Consumption: Approximately 50 Watts

Physical Dimensions

Table Top: 5 3/4" H x 19" W x 19" D, 21.5 lbs.  
Rack Mount: 5 1/2" H x 19" W x 22" D, 21 lbs.  
Circuit Board: 16" x 16"

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